

This paper deals with expressions like:

$$e^{i\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-i\frac{1}{2}\varphi\sigma_3}$$

Note: σ_i are the Pauli matrices.

The solution can be expressed either with trigonometric functions or exponentials.

We will work through this problem with exponential and trigonometric approach. A third and a fourth approach are shown in the end.

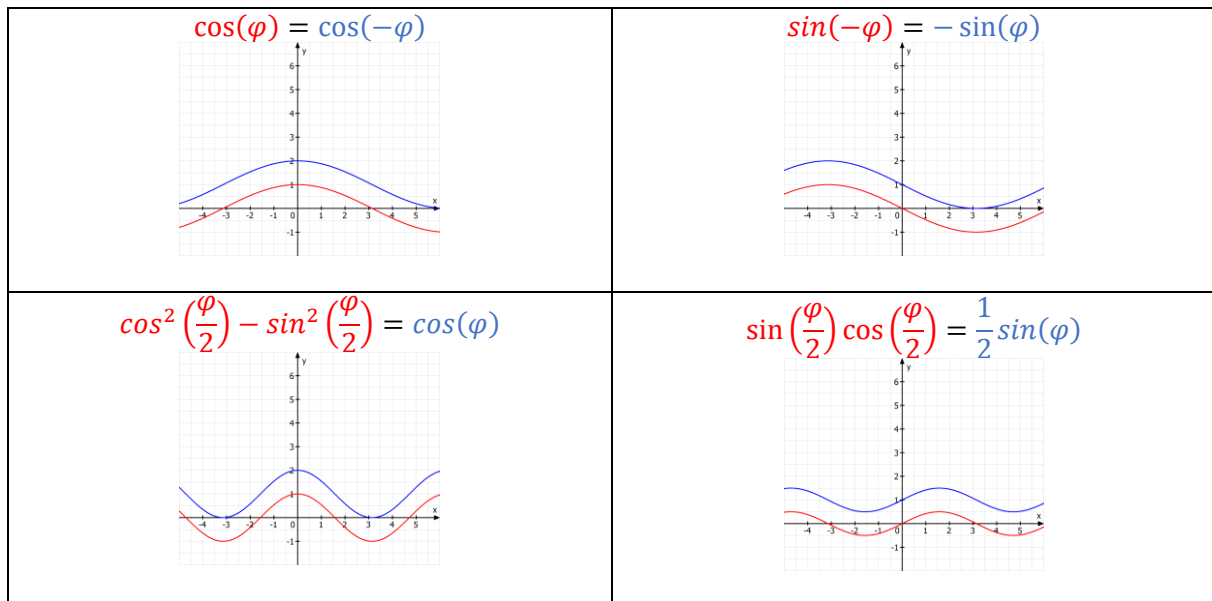
More information you find at

<https://www.math.utah.edu/~gustafso/2250matrixexponential.pdf>

Hope I can help you with learning quantum mechanics.

Prerequisite

The following trigonometric identities hold:



Note: blue functions shifted upwards.

The Pauli-matrices:

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Note: The identity matrix could be regarded as a Pauli matrix: $\sigma_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Note: Pauli-matrices are Hermitian.

For Pauli-matrices holds:

$$\sigma_1^2 = \sigma_2^2 = \sigma_3^2 = id$$

Note: id is the identity matrix

$$\sigma_i \sigma_j = -\sigma_j \sigma_i \text{ for } i \neq j$$

$$[\sigma_i, \sigma_j] = 2i\epsilon_{ijk}\sigma_k$$

$$\sigma_i \sigma_j = \delta_{ij}id + i\epsilon_{ijk}\sigma_k$$

ϵ_{ijk} is the Levi-Civita symbol that controls the \mp -sign:

$$\epsilon_{ijk} = \begin{cases} +1 & \text{if } ijk \text{ is an even permutation of } 123 \\ -1 & \text{if } ijk \text{ is an odd permutation of } 123 \\ 0 & \text{if two indices are the same} \end{cases}$$

Note: Even permutations of $\{123\}$ are $\{123\}, \{231\}, \{312\}$. Odd permutations are $\{132\}, \{321\}, \{213\}$

For a quadratic matrix A holds:

$$\frac{d}{d\varphi} e^{A\varphi} = A \cdot e^{A\varphi}$$

End prerequisite

We treat the expression $e^{\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-\frac{1}{2}\varphi\sigma_3}$ as function of φ :

$$f(\varphi) = e^{\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-\frac{1}{2}\varphi\sigma_3}$$

Note: $f(0) = \sigma_1$

We derivate the function twice to get a differential equation.

First derivative:

$$\begin{aligned} \frac{d}{d\varphi}f(\varphi) &= e^{\frac{1}{2}\varphi\sigma_3}\left(i\frac{1}{2}\sigma_3\right)\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} + e^{\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-\frac{1}{2}\varphi\sigma_3}\left(-i\frac{1}{2}\sigma_3\right) = \\ &= \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}\sigma_3\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} - \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}\sigma_1\sigma_3e^{-\frac{1}{2}\varphi\sigma_3} = \\ &= \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}i\sigma_2e^{-\frac{1}{2}\varphi\sigma_3} - \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}(-i\sigma_2)e^{-\frac{1}{2}\varphi\sigma_3} = \\ &= \frac{i}{2}\left(e^{\frac{1}{2}\varphi\sigma_3}i\sigma_2e^{-\frac{1}{2}\varphi\sigma_3} + e^{\frac{1}{2}\varphi\sigma_3}i\sigma_2e^{-\frac{1}{2}\varphi\sigma_3}\right) = \\ &= -e^{\frac{1}{2}\varphi\sigma_3}\sigma_2e^{-\frac{1}{2}\varphi\sigma_3} \end{aligned}$$

Note: $f'(0) = -\sigma_2$

Second derivative:

$$\begin{aligned} \frac{d^2}{d\varphi^2}f(\varphi) &= \frac{d}{d\varphi}\left(\frac{d}{d\varphi}f(\varphi)\right) = -e^{\frac{1}{2}\varphi\sigma_3}\left(i\frac{1}{2}\sigma_3\right)\sigma_2e^{-\frac{1}{2}\varphi\sigma_3} - e^{\frac{1}{2}\varphi\sigma_3}\sigma_2e^{-\frac{1}{2}\varphi\sigma_3}\left(-i\frac{1}{2}\sigma_3\right) = \\ &= -\frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}\sigma_3\sigma_2e^{-\frac{1}{2}\varphi\sigma_3} + \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}\sigma_2\sigma_3e^{-\frac{1}{2}\varphi\sigma_3} = \\ &= \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}i\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} + \frac{i}{2}e^{\frac{1}{2}\varphi\sigma_3}i\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} = \\ &= -\frac{1}{2}e^{\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} - \frac{1}{2}e^{\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} = \\ &= -e^{\frac{1}{2}\varphi\sigma_3}i\sigma_1e^{-\frac{1}{2}\varphi\sigma_3} \end{aligned}$$

Note: $f''(0) = -\sigma_1$

This resembles the derivation chain of sin and cos.

We get the differential equation:

$$f''(\varphi) = -f(\varphi)$$

Solution with exponential functions	Solution with trigonometric functions
$f(\varphi) = Ae^{i\varphi} + Be^{-i\varphi}$ $f'(\varphi) = iAe^{i\varphi} - iBe^{-i\varphi}$ $f''(\varphi) = -Ae^{i\varphi} - Be^{-i\varphi}$	$f(\varphi) = \mathcal{A}\sin(\varphi) + \mathcal{B}\cos(\varphi)$ $f'(\varphi) = \mathcal{A}\cos(\varphi) - \mathcal{B}\sin(\varphi)$ $f''(\varphi) = -\mathcal{A}\sin(\varphi) - \mathcal{B}\cos(\varphi)$
We use: $f(0) = \sigma_1$ $\sigma_1 = Ae^{i0} + Be^{-i0}$ $\sigma_1 = A + B$ $f'(0) = -\sigma_2$ $\sigma_2 = iB - iA$ We get for A and B : $A = \sigma_1 - B$ $B = \frac{\sigma_2 + iA}{i} = \frac{\sigma_2 + i(\sigma_1 - B)}{i}$ $B = \frac{\sigma_2}{i} + \sigma_1 - B$ $B = \frac{\sigma_2}{2i} + \frac{\sigma_1}{2}$ $A = \sigma_1 - \frac{\sigma_2}{2i} - \frac{\sigma_1}{2} = \frac{\sigma_1}{2} - \frac{\sigma_2}{2i}$	We use: $f(0) = \sigma_1 \rightarrow$ $\sigma_1 = \mathcal{B}$ $f'(0) = -\sigma_2 \rightarrow$ $-\sigma_2 = \mathcal{A}$
Solution: $f(\varphi) = \left(\frac{\sigma_1}{2} - \frac{\sigma_2}{2i}\right)e^{i\varphi} + \left(\frac{\sigma_2}{2i} + \frac{\sigma_1}{2}\right)e^{-i\varphi}$	Solution: $f(\varphi) = \sigma_1\cos(\varphi) - \sigma_2\sin(\varphi)$

We check whether the solutions are different and rewrite the exponential solution in the cartesian representation. For simplicity we use:

$$a := \left(\frac{\sigma_1}{2} - \frac{\sigma_2}{2i}\right)$$

$$b := \left(\frac{\sigma_2}{2i} + \frac{\sigma_1}{2}\right)$$

$$f(\varphi) = ae^{i\varphi} + be^{-i\varphi} =$$

$$a \cdot \cos(\varphi) + i \cdot a \cdot \sin(\varphi) + b \cdot \cos(\varphi) - i \cdot b \cdot \sin(\varphi) =$$

$$(a + b)\cos(\varphi) + i(a - b)\sin(\varphi) =;$$

We replace a and b by their originals:

$$\left(\frac{\sigma_1}{2} - \frac{\sigma_2}{2i} + \frac{\sigma_2}{2i} + \frac{\sigma_1}{2}\right)\cos(\varphi) + i\left(\frac{\sigma_1}{2} - \frac{\sigma_2}{2i} - \frac{\sigma_2}{2i} - \frac{\sigma_1}{2}\right)\sin(\varphi) =$$

$$\sigma_1\cos(\varphi) - \sigma_2\sin(\varphi)$$

The Ansatz with exponential functions gives the same result – the trigonometric way is faster in this case.

Third approach: For involutory matrices P like the Pauli matrices holds:

$$e^{iP\varphi} = \cos(\varphi) \cdot id + i \cdot P \cdot \sin(\varphi)$$

Note: an involutory matrix is its own inverse.

Note: id is the identity matrix.

With this we can work through our problem:

$$e^{i\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-i\frac{1}{2}\varphi\sigma_3} \rightarrow \left(\cos\left(\frac{\varphi}{2}\right) \cdot id + i \cdot \sigma_3 \cdot \sin\left(\frac{\varphi}{2}\right)\right)\sigma_1\left(\cos\left(\frac{\varphi}{2}\right) \cdot id - i \cdot \sigma_3 \cdot \sin\left(\frac{\varphi}{2}\right)\right)$$

After some lengthy calculation and use of the trigonometric identities of the prerequisite we will arrive at the known result:

$$e^{i\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-i\frac{1}{2}\varphi\sigma_3} = \sigma_1\cos(\varphi) - \sigma_2\sin(\varphi)$$

Fourth approach: For diagonal matrices holds:

$$e^{\begin{pmatrix} a & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & n \end{pmatrix}} = \begin{pmatrix} e^a & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & e^n \end{pmatrix}$$

σ_3 is a diagonal matrix:

$$\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

In this case we get:

$$\begin{aligned} e^{i\frac{1}{2}\varphi\sigma_3}\sigma_1e^{-i\frac{1}{2}\varphi\sigma_3} &= \\ e^{i\frac{1}{2}\varphi\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}}\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}e^{-i\frac{1}{2}\varphi\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}} &= \\ \begin{pmatrix} e^{i\frac{1}{2}\varphi} & 0 \\ 0 & e^{-i\frac{1}{2}\varphi} \end{pmatrix}\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}\begin{pmatrix} e^{-i\frac{1}{2}\varphi} & 0 \\ 0 & e^{i\frac{1}{2}\varphi} \end{pmatrix} &= \\ \dots &= \\ \begin{pmatrix} 0 & e^{i\varphi} \\ e^{-i\varphi} & 0 \end{pmatrix} &= \\ \begin{pmatrix} 0 & \cos(\varphi) + i \cdot \sin(\varphi) \\ \cos(\varphi) - i \cdot \sin(\varphi) & 0 \end{pmatrix} &= \\ \begin{pmatrix} 0 & \cos(\varphi) \\ \cos(\varphi) & 0 \end{pmatrix} + \begin{pmatrix} 0 & i \cdot \sin(\varphi) \\ -i \cdot \sin(\varphi) & 0 \end{pmatrix} &= \\ \cos(\varphi)\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \sin(\varphi)\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} &= \\ \cos(\varphi)\sigma_1 - \sin(\varphi)\sigma_2 & \end{aligned}$$